

Basic Properties of a Time Series II

A time series is simply a discrete time stochastic process

$\{X_t, t \in \mathbb{Z}\}$. (\mathbb{Z} is the set of integers $0, \pm 1, \pm 2, \dots$)

We will assume that $\{X_t, t \in \mathbb{Z}\}$ is a second-order process, that is,

$$E[X_t^2] < \infty$$

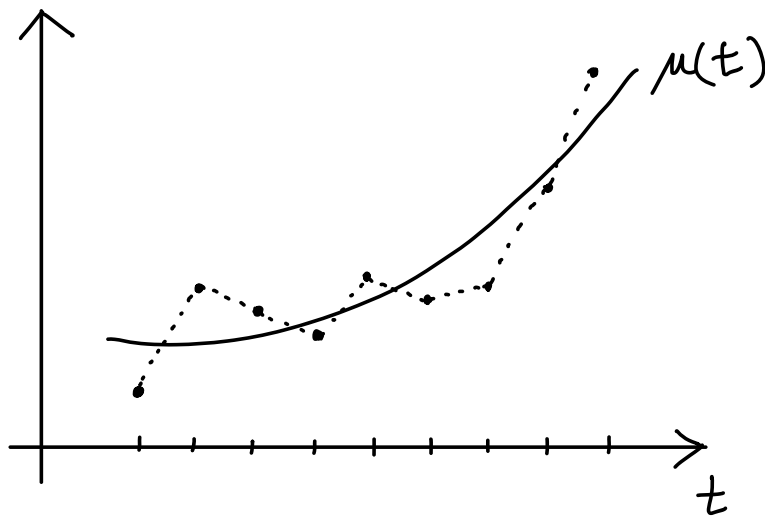
for all $t \in \mathbb{Z}$.

II

Mean Function

The mean function $\mu(t)$, $t \in \mathbb{Z}$ of a time series is defined by

$$\mu(t) = \mathbb{E}[X_t].$$



(II)

Covariance Function

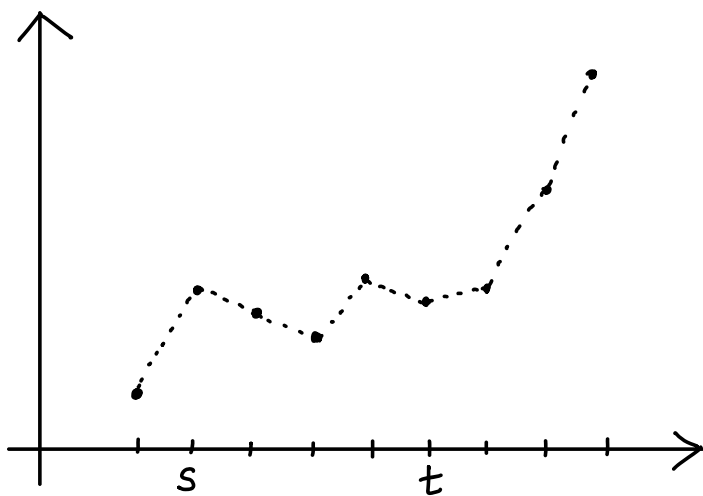
The (auto) covariance function of a time series $\{X_t, t \in \mathbb{Z}\}$ is

$$\gamma(s, t) = \text{Cov}(X_s, X_t)$$

$$:= \mathbb{E}[(X_s - \mu(s))(X_t - \mu(t))]$$

$$= \mathbb{E}[X_s X_t] - \mu(s)\mu(t).$$

$s, t \in \mathbb{Z}$

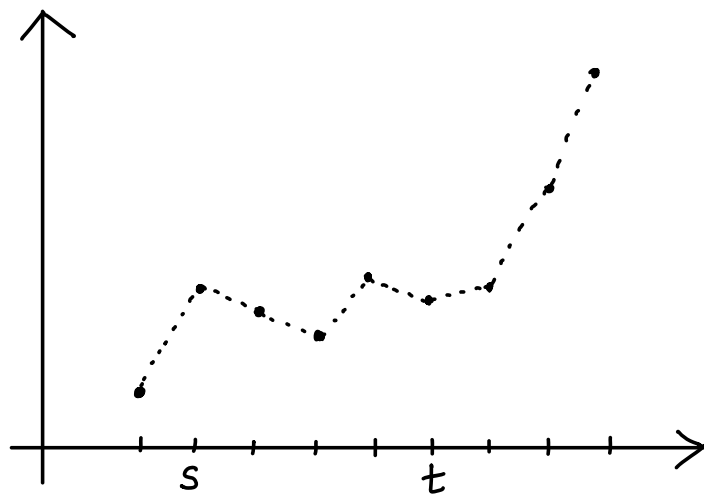


II

Covariance Function

Notice:

$$\begin{aligned}\text{Var}(X_s) &= \text{Cov}(X_s, X_s) \\ &=: \gamma(s, s) \\ &=: \gamma(s), \quad s \in \mathbb{Z}\end{aligned}$$



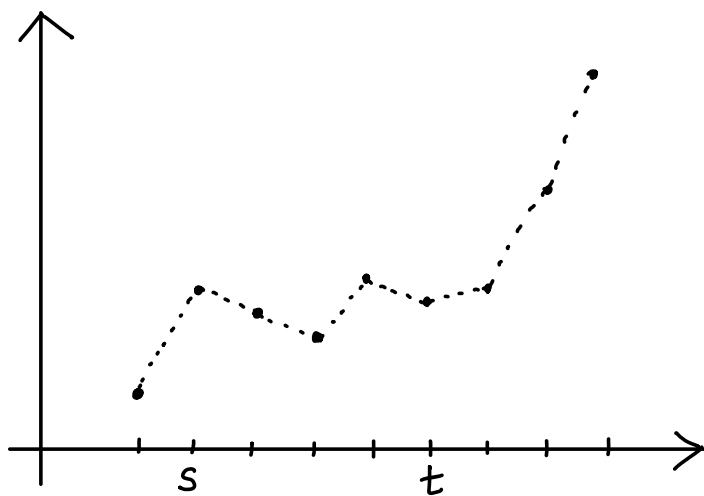
(II)

Correlation Function

The (auto) correlation function of a time series $\{X_t, t \in \mathbb{Z}\}$ is

$$\rho(s, t) = \text{Corr}(X_s, X_t)$$

$$:= \frac{\gamma(s, t)}{\sqrt{\gamma(s) \gamma(t)}} \quad s, t \in \mathbb{Z}$$



(II)

Example 1 (Coin Flips)

Suppose $Y_t, t \in \mathbb{Z}$ are
independent and identically distributed
with

$$Y_t = \begin{cases} -1 & \text{w.p. } 1-p \\ 1 & \text{w.p. } p. \end{cases}$$

- (i) What is the mean function of $\{Y_t, t \in \mathbb{Z}\}$?
- (ii) What is the correlation function of $\{Y_t, t \in \mathbb{Z}\}$?

(II)

Example 2 (Random Walk)

Let $Y_t, t \in \mathbb{Z}^+$ be as in the previous example. ($\mathbb{Z}^+ := 0, 1, 2, \dots$)

Define

$$X_t = X_{t-1} + Y_t, t \in \{1, 2, \dots\}$$

$$X_0 = 0.$$

(i) What is the mean function of $\{X_t, t \in \mathbb{Z}\}$?

(ii) What is the correlation function of $\{X_t, t \in \mathbb{Z}\}$?

(II)

The mean function:

$$\underbrace{\mu(t)}_{\rightarrow E[X_t]} = 0 \quad t \in \mathbb{Z}^+$$

Proof?

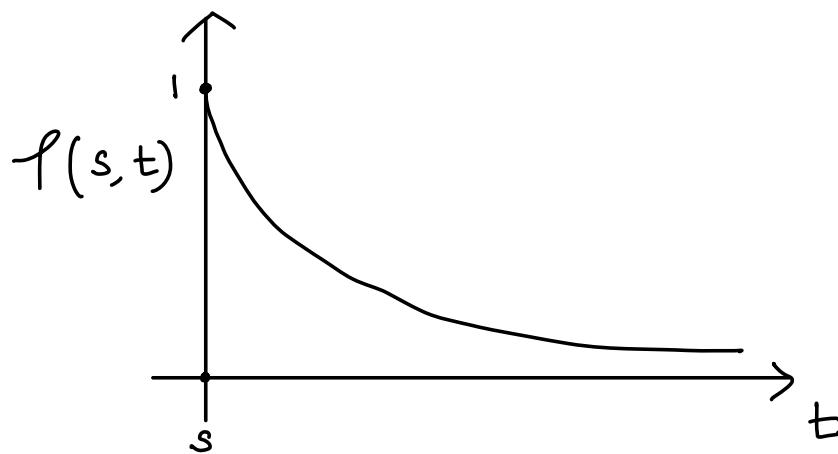
The auto correlation function:

$$\rho(s, t) = \sqrt{\frac{\min(s, t)}{\max(s, t)}}, \quad s, t \in \{1, 2, \dots\}$$

Proof?

(II)

For the (discrete) random walk, the (auto) correlation function looks like:



II

Generating a Random Walk

initialize seed

set.seed(420)

generate coin flips

$Y \leftarrow \text{rbinom}(100, 1, 0.4)$

convert to 1s and -1s

$Y \leftarrow 2 * Y - 1$

initialize the walk

$X \leftarrow \text{rep}(0, 100)$

create the walk

for i in 2:100

{ $X[t] \leftarrow X[t-1] + Y[t]$

}

(II)

Example 3 (Moving Average)

Suppose the random variables in the discrete time stochastic process $\{X_t, t \in \mathbb{Z}^+\}$ are related as follows:

$$X_t = c_0 + \frac{1}{2}(\varepsilon_t + \varepsilon_{t-1}), \quad t = 1, 2, \dots$$

$$X_0 = 0.$$

$$\varepsilon_t \text{ are iid; } E[\varepsilon_t] = 0; \text{Var}(\varepsilon_t) = \sigma_\varepsilon^2$$

(The above "relationships" are sometimes collectively called a "model"; c_0 and σ_ε^2 are called model parameters.)

II

Let's calculate the mean and auto covariance and auto correlation functions.

$$\mu(t) = c_0, \quad t = 2, 3, \dots$$

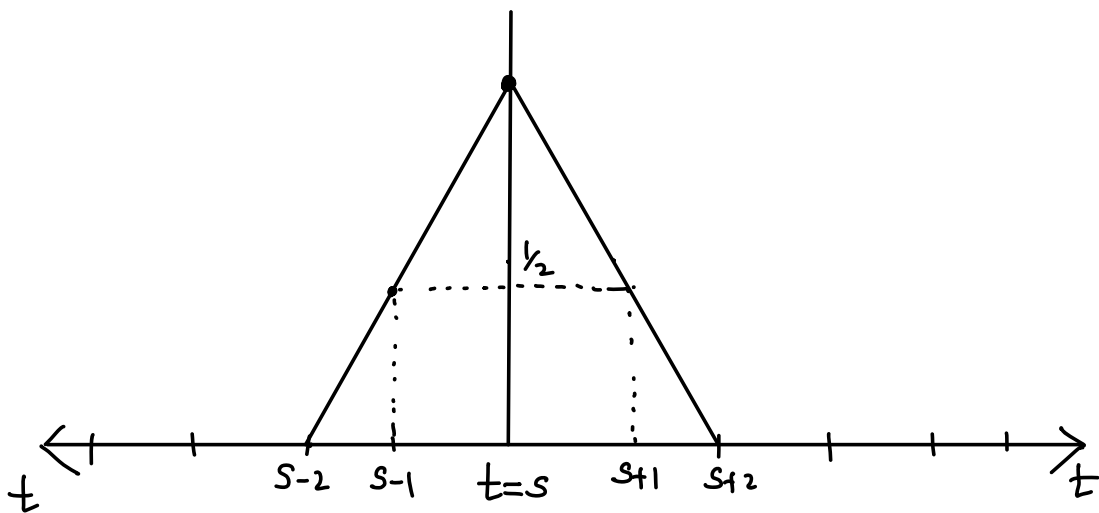
$$\gamma(s, t) = \begin{cases} \sigma_\varepsilon^2/2 & |s-t| = 0 \\ \sigma_\varepsilon^2/4 & |s-t| = 1 \\ 0 & |s-t| > 1 \end{cases}$$

$$\rho(s, t) = \begin{cases} 1 & |s-t| = 0 \\ 1/2 & |s-t| = 1 \\ 0 & |s-t| > 1 \end{cases}$$

Proof?

II

How does the autocorrelation function look?



More Intuition: Can we simulate $\textcircled{\text{II}}$
data from this process?

generate the ε terms

$$\varepsilon \leftarrow \text{rnorm}(100, 0, 2)$$

initialize the series

$$X \leftarrow \text{rep}(0, 100)$$

choose constant

$$C_0 \leftarrow 1$$

create the series

for t in $2:100$

$$\left\{ \begin{array}{l} X[t] \leftarrow C_0 + \frac{1}{2} \times (\varepsilon[t] + \varepsilon[t-1]) \\ \end{array} \right\}$$

II

Let's make sure we understand some properties of the covariance function.

$$(i) \quad \gamma(s, t) \stackrel{?}{=} \gamma(t, s)$$

$$(ii) \quad \gamma(s, t) \stackrel{?}{=} \gamma(0, t-s)$$

$$(iii) \quad \gamma(s, t) \stackrel{?}{=} \gamma(s+\tau, t+\tau)$$

(II)

Second Order Stationary or Covariance Stationary Processes

A discrete-time stochastic process $\{X_t, t \in \mathbb{Z}\}$ is

said to be covariance stationary

if $\{X_{t+\tau}, t \in \mathbb{Z}\}$ and

$\{X_t, t \in \mathbb{Z}\}$ have the same

mean and covariance functions

for all $\tau \in \mathbb{Z}$.

II

In other words, covariance stationary means:

$$\text{I} \quad \mu(t + \tau) = \mu(t) \quad \forall \tau \in \mathbb{Z}$$

$$\text{II} \quad \gamma(s + \tau, t + \tau) = \gamma(s, t) \quad \forall \tau \in \mathbb{Z}$$

(any fixed s, t)

The first condition is easy to interpret.

The second condition can be "tricky."

Best to interpret as "covariance

between random variables is dependent

only on the time lag $|t-s|$, but not

on t, s ."

(II)

For the "moving average" example recall the mean and the covariance functions that we calculated.

$$\mu(t) = c_0, \quad t = 2, 3, \dots$$

$$\gamma(s, t) = \begin{cases} \sigma_\varepsilon^2/2 & |s-t| = 0 \\ \sigma_\varepsilon^2/4 & |s-t| = 1 \\ 0 & |s-t| > 1 \end{cases}$$

$$\rho(s, t) = \begin{cases} 1 & |s-t| = 0 \\ 1/2 & |s-t| = 1 \\ 0 & |s-t| > 1 \end{cases}$$

In general if a process (II)

$\{X_t, t \in \mathbb{Z}\}$ is covariance

stationary, then

$$(i) \mu(t) \equiv \mu$$

$$(ii) \gamma(s, t) = \gamma(0, t-s) \\ \equiv \gamma(h),$$

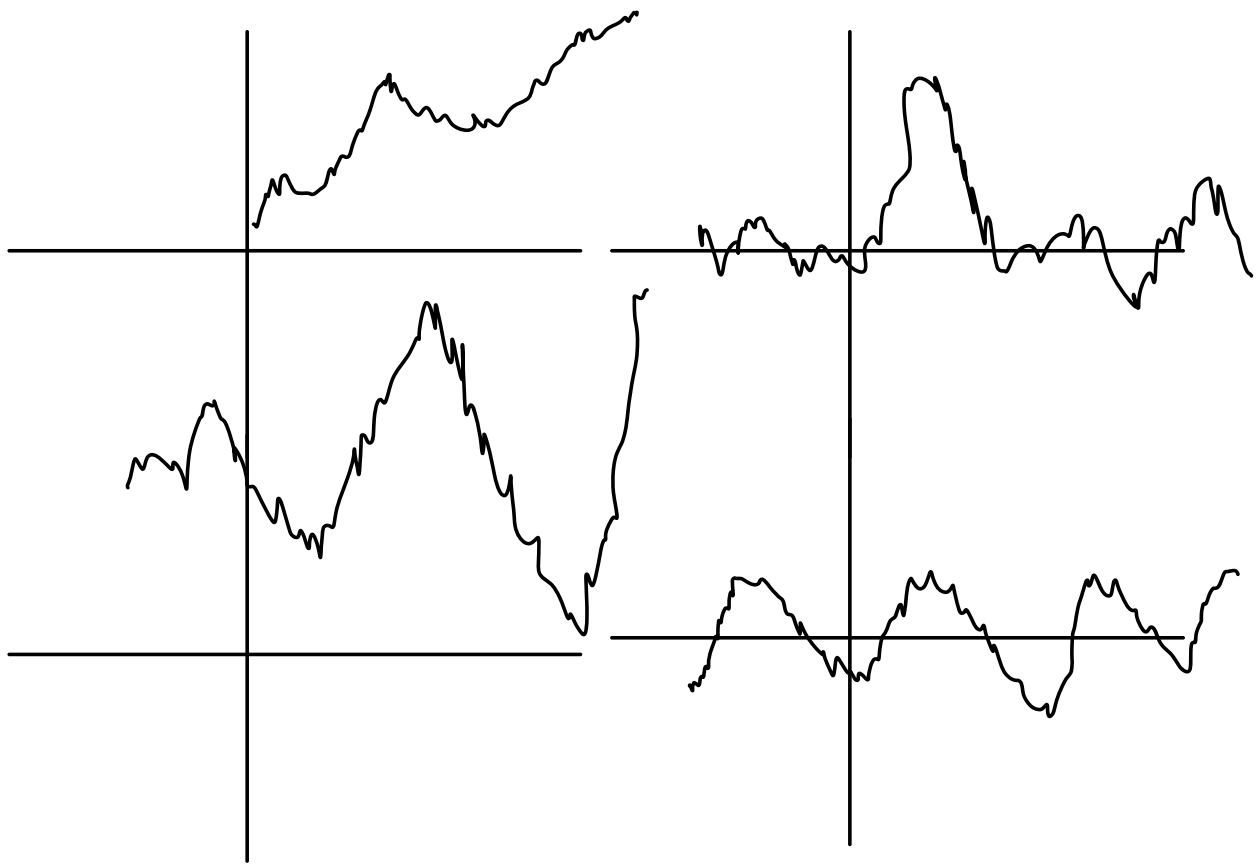
where h is called the "lag."

$$(iii) f(s, t) \equiv f(h).$$

(since $\gamma(h) = \gamma(-h)$, it is sufficient to consider $h \geq 0$.)

(II)

How do time series generated
from a covariance stationary
process look?



(II)

Which of the following series are covariance stationary?

I. $X_t = 0.2 X_{t-1} + \varepsilon_t$

II. $X_t = 0.1t + 0.2 X_{t-1} + \varepsilon_t$

III. $X_t = X_{t-1} + \varepsilon_t$

IV. $X_t = 2 \sin\left(2\pi\left(\frac{t}{6} + Y\right)\right)$
 $Y \sim \text{Unif}(0, 1).$

(Assume $\varepsilon_t \stackrel{\text{iid}}{\sim} N(0, 1)$, $t \in \mathbb{Z}^+$
and $X_0 = 0$.)

If the time series (II)

$\{X_t, t \in \mathbb{Z}\}$ is covariance

stationary, then which of

the following are true?

(i) $\mu(0) \stackrel{?}{=} \mu(t)$

(ii) $f(s, t) \stackrel{?}{=} f(-s, -t)$

(iii) $f(s, t) \stackrel{?}{=} f(-s, t)$

(iv) $f(0, h) \stackrel{?}{=} f(-h, 0)$

II

Example

Consider the time series

$$X_t = 2 \cos\left(2\pi\left(\frac{t}{12} + U\right)\right),$$

$$t \in \mathbb{Z}$$

(i) Find the mean and autocorrelation functions

(ii) Is $\{X_t, t \in \mathbb{Z}\}$ cov. stationary?

II

A process $\{X_t, t \in \mathbb{Z}\}$ is
said to be strictly stationary
if $(X_{t_1}, X_{t_2}, \dots, X_{t_n})$ and
 $(X_{t_1+\tau}, X_{t_2+\tau}, \dots, X_{t_n+\tau})$ have
the same joint distribution,
for all t_1, t_2, \dots, t_n .

(II)

Mind the Difference.

Covariance Stationary

$$\{X_t, t \in \mathbb{Z}\} \text{ and } \{X_{t+\tau}, t \in \mathbb{Z}\}$$

have the same mean and covariance functions. $\forall \tau \in \mathbb{Z}$.

Strictly Stationary

$(X_{t_1}, X_{t_2}, \dots, X_{t_n})$ & $(X_{t_1+\tau}, X_{t_2+\tau}, \dots, X_{t_n+\tau})$
have the same joint distribution.

II

Differencing and Backshift

"Differencing" is an operation on a time series, often in an attempt to stationarize it.

Differencing is denoted (II)

by ∇X_t :

$$\nabla X_t = X_t - X_{t-1}$$

$$\nabla^2 X_t = \nabla(\nabla X_t)$$

$$= \nabla(X_t - X_{t-1})$$

$$= X_t - 2X_{t-1} + X_{t-2}$$

⋮

(II)

Backshift is denoted by

BX_t :

$$BX_t = X_{t-1}$$

So,

$$\nabla X_t = X_t - X_{t-1} = (1-B)X_t$$

$$\begin{aligned}(1-B)^2 X_t &= (1-2B+B^2)X_t \\ &= \nabla^2 X_t.\end{aligned}$$

II

Differencing m times
is "multiplying" by

$(1-B)^m$:

$$\nabla^m X_t = (1-B)^m X_t.$$

II

EXAMPLE

Find the mean and
auto covariance functions

of $Y_t := \nabla \varepsilon_t, t \in \mathbb{Z}$

where $\{\varepsilon_t, t \in \mathbb{Z}\}$ is

White noise.

EXAMPLE

(II)

Suppose

$$Y_t = \beta_0 + \beta_1 t + X_t, t \in \mathbb{Z}$$

where $\{X_t, t \in \mathbb{Z}\}$ is

mean-zero and cov. stat.

with lag- k autocov $\gamma(k)$.

1. Show that $\{Y_t, t \in \mathbb{Z}\}$
is not cov. stat.

2. Show that ∇Y_t is cov. stat

II

In the previous problem,
suppose

$$Y_t = f(t) + X_t.$$

$$\text{and } f(t) = a_0 t^m + a_1 t^{m-1} + \dots + a_m.$$

Then, $\nabla^n Y_t$ is cov. stat

if $n \geq m$ and not cov. stat

if $n < m$.

Sample Estimators

(II)

If $\{X_t, t \in \mathbb{Z}\}$ is covariance stationary, then

$$(i) \mu(t) = \mu \quad \forall t \in \mathbb{Z}$$

$$(ii) \gamma(s, t) = \gamma(0, |s-t|) \\ \equiv \gamma(h), h=0, 1, \dots$$

↪ "lag"

$$(iii) f(s, t) = f(0, |s-t|) \\ \equiv f(h), h=0, 1, \dots$$

Can μ , $\gamma(\cdot)$, & $f(\cdot)$ be estimated?

Suppose $\{X_t, t=1, 2, \dots\}$ ^{II}

is covariance stationary and

X_1, X_2, \dots, X_n are the first n observations.

We want to estimate

$\mu, \gamma(h), \rho(h)$:

$$\mu = \mathbb{E}[X_t]$$

$$\gamma(h) = \text{Cov}(X_t, X_{t+h})$$

$$\rho(h) = \gamma(h)/\gamma(0)$$

(II)

$$\hat{\mu}(t) = \hat{\mu} = \frac{1}{n} \sum_{j=1}^n X_j$$

$$\hat{\gamma}(h) = \frac{1}{n-h} \sum_{j=1}^{n-h} (X_j - \hat{\mu})(X_{j+h} - \hat{\mu})$$

$$h = 0, 1, 2, \dots, n-1$$

$$\hat{\rho}(h) = \frac{\hat{\gamma}(h)}{\hat{\gamma}(0)}, \quad h = 0, 1, \dots, n-1$$

Beware of Dependence

(II)

During Estimation

Let's take an example.

Suppose:

$$Y_t = \mu + X_t, \quad t \in \mathbb{Z}$$

where $\{X_t, t \in \mathbb{Z}\}$ is a covariance stationary time

series with autocovariance function

$\gamma(h), h \geq 0$, and zero mean.

Beware of Dependence During Estimation

(II)

We do not know μ and $\gamma(h)$, $h \geq 0$ and so we want to estimate these from "data".

Suppose we have observed data

$$Y_1, Y_2, \dots, Y_n$$

Beware of Dependence (II)
During Estimation

Notice that the mean function

$$\mu(t) = \mathbb{E}[Y_t] = \mu + 0$$

$$\Rightarrow \mu(t) = \mu \quad \forall t \in \mathbb{Z}.$$

Hence,

$$\hat{\mu} = \frac{1}{n} \sum_{j=1}^n Y_{j,d}$$

Beware of Dependence During Estimation

(II)

Let's see how sure we can be about $\hat{\mu}$.

$$\begin{aligned}\text{Var}(\hat{\mu}) &= \text{Var}\left(\frac{1}{n} \sum_{d=1}^n Y_{d.}\right) \\ &= \frac{1}{n^2} \text{Var}\left(\sum_{d=1}^n Y_{d.}\right)\end{aligned}$$

Beware of Dependence
During Estimation

II

$$\text{Var}(\hat{\mu}) = \frac{\gamma(0)}{n} \left(1 + 2 \sum_{h=1}^{n-1} \left(1 - \frac{h}{n} \right) \rho(h) \right)$$

(Make sure you understand how
I got the above expression.)

Beware of Dependence

(II)

During Estimation

When n is large, and

$$\sum_{h=1}^{\infty} |f(h)| < \infty,$$

$$\text{Var}(\hat{\mu}) \approx \frac{\gamma(0)}{n} \sum_{h=-\infty}^{\infty} f(h).$$

e.g., if $f(h) = \phi^h$, $h \geq 0$,

then

$$\text{Var}(\hat{\mu}) \approx \frac{\gamma(0)}{n} \left(\frac{1+\phi}{1-\phi} \right).$$